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<p>(54) Title: <b>COMPUTERIZED AUTOMOTIVE SERVICE EQUIPMENT USING MULTI-POINT SERIAL LINK DATA TRANSMISSION PROTOCOLS</b></p> <p>(57) Abstract</p> <p>A multi-point serial link protocol, such as USB, is used to transfer vehicle diagnostic information back and forth between vehicle diagnostic sensors and a host computer. Multiple distinct vehicle servicing applications may be added to or removed from the service bay without requiring substantial software changes or revisions. The amount of vehicle diagnostic hardware is also minimized. The multi-point serial link may originate in the vehicle's on-board computer, allowing the vehicle itself to function as a data hub for the diagnostic automotive service sensors.</p>		

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likely be required to configure the computer to support the connection of a sensor system.

An add-in sensor interface board allows very fast access to sensor information. Unfortunately, adding this board to a PC still requires a person knowledgeable of the computer to configure addresses and interrupts so there are no conflicts. Additionally, the physical layout of expansion slots is subject to change over time as newer models and protocols are developed, leading to obsolescence of current interface board specifications. Typically operating systems have no built-in support for a custom add-in board. Thus complex software must be written allowing the operating system and the automotive service program to communicate with the add-in board. This complex software must be re-written with the introduction of new, updated operating systems.

Still another problem in current systems exists when a single PC is required to support multiple sensor systems such as a wheel aligner combined with an engine analyzer. A PC has a limit to the number of add-in interface boards that can be added. There is a finite number of I/O addresses and interrupts that are available and once all of them are used, no additional boards may be added. The same problem exists if serial communications ports or parallel printer ports are used. Once the supported ports are used, it is difficult to add more. Furthermore, repair or replacement of interface boards may require specialized computer training for the automotive service technicians.

### DESCRIPTION OF THE PRIOR ART

Automotive service equipment of the prior art have until recently used special purpose microprocessors or custom designed computer systems to process the electronic data signals generated by sensors for the purpose of facilitating servicing and repair of automobiles. These proprietary designed systems were optimized for data acquisition of particular automotive service systems sensors. For instance, automotive service systems designed for wheel alignment were designed specifically to acquire data from alignment sensors and display information and data related to wheel alignment.

Figure 1 shows a typical arrangement. Special purpose computer 10 includes a microprocessor 14 and a data acquisition means 12, for example various hard wired ports associated with the special purpose computer 10. Automotive service system data sensors 16 are coupled to the data acquisition means 12 via appropriate cabling. Display 18 is connected to computer 10 and used as an operator interface.

Later, general purpose computers were used, such as IBM PC compatibles and other brands. General purpose computers of the prior art were not specifically designed for fast data acquisition from sensors and provided only standard serial point-to-point communications via RS-232 protocols, or standard "Centronics" style parallel port communications. Using the serial communications port or the parallel printer port was slow, and generally supported only one device.

Figure 2 shows a typical arrangement. General purpose computer 20 is an IBM or Apple compatible. Computer 20 includes a microprocessor 22 and a standard UART communications port 24. Associated with the system is external sensor interface board 26, which contains its own UART 28 for transmission to UART 24. Sensors 32, 34, 36 and 38 are connected to the interface board 26 via input port means 30 with a standard hard wired connection.

U.S. Patent No. 5,734,569, assigned to the assignee herein and hereby incorporated by reference, discloses fast sensor data acquisition on a general purpose computer. It discloses a system that circumvents some of the disadvantages of the use of the serial and parallel ports by connecting directly to the ISA or PCI ports inside the computer. Figure 3 shows generally how this worked. General purpose computer 40 contains a microprocessor 42 and one of a plurality of expansion slots 46, connected to the microprocessor 42 via synchronous parallel data paths 44. Sensor interface board 48 plugs into the expansion slot 46. Board 48 contains a dual port RAM 50 that receives sensor data from automotive service system sensors 56 through UART 54 and microcontroller 52, both also residing on board 48. Dual port RAM occupies logical address space in computer 40, and thereby enables data acquisition speed on the order of the speed with which the microprocessor 42 accesses its own memory. Still, board 48 suffers from the deficiencies noted above, particularly limitation on expandability.

Another prior art arrangement utilizes a SCSI interface. The arrangement is shown generally in Figure 4. Data acquisition unit 64 acquires sensor data from engine analyzer sensors 66. The unit 64 is connected to the SCSI interface of add-in board 62. This standard SCSI interface is a fast parallel type of interface for transmitting data between computer 60 and multiple external peripherals. This other prior art arrangement suffers from the same infirmities noted above with respect to hardware interface boards.

### OBJECTS OF THE INVENTION

10 It is an object of the present invention to overcome the disadvantages of the prior art. More specifically, it is an object of the present invention to provide an improved computerized automotive service equipment system.

It is further an object of the invention to integrate a general purpose computer into automotive service equipment in a manner permitting multiple automotive service functions to reside on a single general purpose computer.

15 It is another object of the invention to provide a high speed multi-point serial link on an automotive service equipment sensor interface board that is easily connected to a general purpose computer through an operating system supported by an industry standard serial interface protocol.

20 It is still another object of the invention to provide automotive service equipment having a general purpose computer that can accommodate multiple sensor systems that all may be connected or disconnected without disassembling the general purpose computer.

It is another object of the invention to provide automotive service equipment where implementing the interface between the sensors and the general purpose computer does not require extensive knowledge of the low level computer architecture of the general purpose computer.

25 It is yet another object of the invention to reduce software complexity and development time for such automotive service equipment through the use of a serial transmission protocol that is physically and functionally expandable.

It is a further object of the invention to provide automotive service equipment having sensors that are directly connected into a system computer without the use of intervening hardware.

It is yet another object of the invention to provide a serial interface protocol  
5 for computerized automotive service equipment in which mixed mode isochronous data transfers and asynchronous messaging is enabled.

It is still a further object of the invention to provide automotive service equipment in which the sensors are dynamically attachable and reconfigurable.

It is yet another object of the invention to provide an automotive service  
10 system having a standard high-speed multi-point serial link to the data stream of the vehicle's on-board computers system.

### SUMMARY OF THE INVENTION

The inventions are defined by the appended claims. For ease of reference,  
15 certain features thereof are summarized here.

The present invention comprises a vehicle diagnostic system having a general purpose computer, the computer capable of executing a vehicle diagnostic application and serving as a host for a multi-point serial link protocol, such as USB; a multi-point serial link operably coupled to the computer and having at least one port; at  
20 least one vehicle diagnostic sensor and/or data connection to the vehicle's on-board computer system operably coupled to the multi-point serial link through the respective port and each capable of sensing a vehicle diagnostic state. A change in the vehicle diagnostic state associated with the vehicle computer data or any one sensor provides an interrupt to the computer through the multi-point serial link.

25 In another aspect, the present invention comprises a vehicle diagnostic system having a general purpose computer, the computer capable of executing a vehicle diagnostic application and serving as a host for a multi-point serial link protocol, such as USB; a multi-point serial link operably coupled to the computer and having at least one port; at least one vehicle diagnostic sensor and/or a data  
30 connection to the vehicle's on-board computer system, operably coupled to the multi-point serial link through the respective port and capable of sensing a vehicle diagnostic state. The computer polls the vehicle computer data link or at least one

sensor within a predetermined period of time and the vehicle computer data link or the respective sensors return a message to the computer through the hub indicative of the vehicle diagnostic state associated with vehicle computer data or the respective sensors.

5           In another aspect, the invention comprises a vehicle diagnostic system having a general purpose computer, the computer capable of executing a vehicle diagnostic application and serving as a host for multi-point serial link protocol, such as USB; a multi-point serial link operably coupled to the computer and having at least one port; at least one vehicle diagnostic sensor and/or a data connection to the vehicle's on-board computer system, operably coupled to the multi-point serial link through the  
10           respective port and capable of sensing a vehicle diagnostic state. The computer is capable of instantaneously detecting the addition or removal of the vehicle on-board computer communications link or sensor to and from a port and indicating such addition or removal to the vehicle diagnostic application.

15           In still a further aspect, the invention comprises a vehicle diagnostic system having a general purpose computer, the computer capable of executing a vehicle diagnostic application and serving as a host for a multi-point serial link protocol, such as USB; a hardware interface board comprising a RAM and a plurality of externally accessible serial communication ports, the RAM being shared by a multi-point serial  
20           link controller operably coupled between the computer and the RAM and a serial communications controller operably coupled to the plurality of ports; at least one vehicle diagnostic sensor and/or a data connection to the vehicle's on-board computer system, operably coupled to the link through the respective plurality of ports and each capable of sensing a vehicle diagnostic state associated with each respective sensor or  
25           data stream of the vehicle's on-board computer system. The serial communications controller periodically senses the vehicle diagnostic state at the at least one sensor or from the vehicle's on-board computer, and stores the vehicle diagnostic state in the RAM for access by the multi-point serial link controller.

          In still a further aspect, the invention comprises a vehicle diagnostic system  
30           having a general purpose computer, the computer capable of executing a vehicle diagnostic application and serving as a host for multi-point serial link protocol, such as USB; a hardware interface board comprising interface logic and at least one



externally accessible serial communication port, the interface logic being shared by a multi-point serial link controller, the multi-point serial link controller also operably coupled between the general purpose computer and the serial communications controller operably coupled to the at least one port; a plurality of vehicle diagnostic sensors or a connection to the vehicle on-board computer operably coupled to the interface board through the respective at least one port and each capable of sensing or responding to a vehicle diagnostic state associated with each respective sensor or connection to the vehicle on-board computer. The serial communications controller periodically senses the vehicle diagnostic state at each of the at least one sensors or vehicle computer link and passes the vehicle diagnostic state to the multi-point serial link controller for transmission to the computer.

In yet another aspect, the invention comprises a vehicle diagnostic system having a general purpose computer, the computer capable of executing a vehicle diagnostic application and serving as a host for multi-point serial link protocol, such as USB; a multi-point serial link operably coupled to the computer and having at least one port; at least one vehicle diagnostic sensor and/or a data connection to the vehicle's on-board computer system operably coupled to the multi-point serial link through the respective at least one port and each capable of sensing a vehicle diagnostic state through electrical coupling means capable of extending at least sixty feet from the general purpose computer.

In a still further aspect, the invention comprises a vehicle diagnostic system having a general purpose computer, the computer capable of executing a vehicle diagnostic application and serving as a host for a multi-point serial link protocol, such as USB; at least one vehicle diagnostic sensor and/or a data connection to the vehicle's on-board computer system comprising a multi-point serial link operably coupled to the general purpose computer and capable of sensing a vehicle diagnostic state. Each of the sensors or vehicle computer data connections comprises detection means for providing a stream of data indicative of the vehicle diagnostic state to its respective multi-point serial link for later communication to the computer, whereby the computer may provide the stream of data to the vehicle diagnostic application after receipt from the respective link.

## DESCRIPTION OF THE FIGURES

Figs. 1-4 are diagrammatic representations of various prior art systems.

Figs. 5-8 are diagrammatic representations of various exemplary embodiments of the present invention.

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## DETAILED DESCRIPTION

The present invention makes use of a recently developed prior art computerized serial data transmission protocol, the "Universal Serial Bus," or "USB." The protocol is fully described in the Universal Serial Bus Specification, revision 1.0, January 15, 1996, which is hereby incorporated by reference as if fully disclosed herein.

Reference will now be made to Figure 5, which discloses an embodiment of the present invention. The embodiment of Figure 5 is directed to a vehicle wheel alignment application, but it will be appreciated that the same principles are easily applied to other types of computerized automotive service equipment, such as engine analyzers, brake testers, wheel balancers and the like. Further, the term "automotive service equipment" can be understood to refer as well to equipment used to service other types of vehicles as well, such as trucks, vans, motorcycles, boats, airplanes and the like. Likewise, the term "sensor" contemplates any item that is capable of acquiring or receiving vehicle diagnostic information or related signals.

Sensors 115 are vehicle wheel alignment sensors, such as those disclosed in U.S. Patent No. 4,931,964 and 5,208,646; both incorporated herein by reference. In use, sensors 115 are removably mounted to the rims of a vehicle wheel under test, and detect the alignment angles of the particular wheel on which they are mounted. They are capable of sensing such alignment angles as toe, camber, caster, SAI, Ackerman angle, and others, as is more fully described in U.S. Patent No. 4,931,964. Sensors 115 each communicate with sensor interface board 110 over a communication medium, preferably a standard serial cable, although infrared and RF techniques are known and interchangeable with the cabling method.

Reference is now made to Figure 6, which contains further detail of the system shown in Figure 5. Serial information about wheel angles first enters board 110 at UART 116 over a standard serial communication protocol, such as RS-232.

Each sensor of the group of sensors 115 is associated with its own UART 116. Microcontroller 114 within board 110 is coupled with interface logic (such as a RAM, a dual port RAM, bus transceivers, and latches, not shown), into each UART 116 and performs two main functions. First, it polls each respective sensor 115 through its UART 116 in a continuous polling cycle. This permits it to obtain the raw signals from sensors 115 that are indicative of the respective wheel angle measurements. During each cycle, the raw angle signals from sensors 115 are each stored in a memory associated with microcontroller 114 (such as a dual port RAM, not shown). Up to this point, the operation of board 110 in this embodiment is similar to that described in U.S. Patent No. 5,734,569. However, sensor interface board 110 also contains its own USB controller 112 operably coupled to the microcontroller 114 by interface logic (including dual-port RAM, not shown). USB controller 112 is available from Cypress Semiconductor Corporation, San Jose, California, as part number CY7C65113. USB controller 112 permits board 110 to constitute a USB "device," as understood in the USB specification, pages 34-37. USB controller 112 is configured to communicate with microcontroller 114 in board 110 to retrieve the raw angle signals for further transmittal as described below.

Referring again to Figure 5, link 105 is shown between board 110 and general purpose computer 100. Link 105 is representative in this embodiment of a high speed multipoint data link, preferably selected from the list comprising Ethernet, CAN, Firewire, Access Bus, Token Ring, Arcnet, Local Talk, FDDI, ATM, and CDDI, and most preferably comprising USB. This high speed multi-port serial link replaces and improves the function of the interface board's dual port RAM as connected to the general purpose computer's parallel synchronous data paths, as disclosed in U.S. Patent No. 5,734,569. The USB protocol is governed by general purpose computer 100, which is assumed to be equipped with USB capability, either within its operating system or added later as an enhancement. Computer 100 contains a USB host controller 102. USB host controller 102 is typically provided by the manufacturer of general purpose computer 100. General purpose computer 100 utilizes the USB protocol to receive the raw angle information from board 110 in one of at least two ways. First, an interrupt method may be used, as described in USB specification, pages 56-58. In the interrupt method, USB controller 112 initiates a

communication with general purpose computer 100 through USB host controller 102 whenever a predetermined condition occurs, such as the change one of the vehicle wheel angles as detected by sensors 115. In this instance, host controller 102 accepts the communication from controller 112 as an interrupt, and directs computer 100 at the appropriate time to pause and take notice of incoming information. Then, a data packet containing the raw angle information is transmitted from controller 112 to host controller 102 over the USB link 105. Computer 100 is now capable of utilizing the raw sensor information in the data packet in the known way to convert it into wheel angle information for use by a vehicle wheel alignment application residing on computer 100, for instance the VISUALINER wheel alignment software available from the John Bean Company. Alternatively, the interrupt method may be used as follows. General purpose computer 100 initiates data acquisition cycles by passing an appropriate command from host controller 102 to USB controller 112. Once the command is received, microcontroller 114 responds by cyclically polling the sensors 115 for raw angle information, on the order of 8-10 times per second. Then on completion of each data acquisition cycle, the microcontroller 114 provides raw angle information to the USB controller 112 which sends an interrupt to the host controller 102, which in turn makes the information available to the automotive service application residing on general purpose computer 100.

In a second embodiment, computer 100 uses the USB protocol to receive raw angle information from board 110 to computer 100 through a USB polling, or messaging, procedure, as described in the USB specification, pages 54-56. This embodiment is distinct from the description above in the following way. Rather than the USB controller 112 sending an interrupt to the host controller 102 after each data acquisition cycle, the host controller 102 polls the USB controller 112 for the same information on a periodic basis as determined by the automotive service equipment application residing on computer 100.

A feature of each embodiment described above is dynamic reconfigurability. This is described in the USB specification, page 28. Sensor interface board 110 acts as a USB "device" because of the presence of USB controller 112. General purpose computer 100 acts as USB "hub" because of the presence of USB host controller 102. It will be appreciated that a host serves as the root hub, and therefore there is always

at least one hub on a USB system. Hubs indicate the attachment or removal of a USB device in its per port status. The host queries the hub to determine the reason for the notification. The hub responds by identifying the port used to attach the USB device. The host enables the port and addresses the USB device with a control pipe using the USB default address. All USB devices are addressed using the USB default address when initially connected or after they have been reset. The host determines if the newly attached USB device is a hub or a device and assigns a unique USB address to the USB device. The host establishes a control pipe for the USB device using the assigned USB address and endpoint number zero. If the attached USB device is a hub and USB devices are attached to its ports, then the above procedure is followed for each of the attached USB devices. If the attached USB device is a function, then attachment notifications will be dispatched by USB software to interested host software.

Figure 7 shows another embodiment of the present invention, in which the USB protocol is extended to the sensors that form part of the automotive service equipment. In this embodiment, sensor 210 is a wheel alignment head, sensor 220 is an engine analyzer pod, and sensor 230 is any other kind of miscellaneous automotive service system data acquisition sensor. Here, multiple types of sensors are shown to illustrate the multitude of servicing features that can be provided to cooperate with automotive service applications on general purpose computer 200 using the USB multi-point high speed serial interface protocol. Another distinction of this embodiment is in its use of USB controllers physically located at the sensors, in contrast to the embodiment described above which used RS-232 serial data transmission at the sensors.

General purpose computer 200 contains multiple automotive service applications, including a vehicle wheel alignment application and an engine analyzer application. Computer 200 is also configured to act as a USB host. As such, it contains master controller 202, and acts as a root hub. Each sensor 210, 220 and 230 can be further described with reference to its parts. Wheel alignment head 210 contains microcontroller 214 coupled both to angle sensor 216 and USB controller 212. Likewise, engine analyzer pod 220 contains microcontroller 224 coupled both to spark sensor 226 and USB controller 222. While the details of generic sensor 230

are not shown, they will be similar to the foregoing for sensors 210 and 220.

Generic sensor 230 will now be addressed in the following remarks. The respective USB controllers 212 and 222 are coupled to master controller 202 over a USB protocol as described before in connection with the embodiment of figures 5 and 6.

5 It will be appreciated that a separate multi-port USB hub (not shown) may be incorporated into the system to accommodate the multiple sensors, and couple them into the USB controller 202. In this manner, sensors 210, 220 and 230 may communicate with the automotive service applications residing on general purpose computer 200 without the need for a separate sensor interface board. Put another  
10 way, the functions of the sensor interface board are incorporated into the respective sensors, thus dispensing with the use of intervening hardware.

Figure 8 shows another embodiment of the present invention. In this embodiment, general purpose computer 300 contains an automotive service equipment application. Associated with this embodiment is multifunction hub 310. Hub 310  
15 contains a USB hub controller 320 and UART 322. Sensors 324, 326, 328 and 330 are coupled to UART 322, which in turn is coupled to controller 320. As described so far, this embodiment functions identically to the embodiment associated with Figures 5 and 6. In addition to the above, however, hub 310 contains a plurality of USB ports 340 which are coupled into controller 320. In this manner, the  
20 embodiment of figure 8 may be used as a combination sensor interface board and USB hub for the connection of additional USB-based automotive service equipment, such as engine analyzers or wheel balancers. Naturally, any other USB-based peripheral may be attached to the ports in this embodiment as well, such as USB-based cameras, printers, modems and so on, as long as the appropriate application  
25 resides on computer 300.

In each of the above embodiments, the data eventually entering computers 100, 200 and 300 may also come directly from a vehicle's on-board computer. For example, the on-board data may be uploaded in the conventional manner via serial transmission to a sensor interface board, and then stored in a dual port RAM. Then,  
30 USB protocols may be used as hereinbefore described to transfer that data next to a host computer for display and analysis by either the computer or the service technician. Alternatively, the vehicle on-board computer data may be transferred

directly by incorporating a USB controller and associated protocol directly into the on-board computer. Thus, a physical or RF/IR data link may be established with a service bay computer, whereupon the on-board computer itself functions as a USB device or hub. If a hub, then wheel alignment/engine analyzer sensors may be linked  
5 directly into the vehicle on-board computer, which thereupon uses USB protocols to transfer the respective sensor data to the host computer.

In each of the above embodiments, general purpose computers 100, 200 and 300 may be located on a repair shop floor several yards away from the sensors that take in the data. Hence, the length of any cabling might exceed the maximum cable  
10 length dictated in the USB specification— 3 feet. Therefore, between any two points in the USB transmission (such as between USB-based sensors and a USB hub, or between USB-based interface board and USB host controller), line driver devices are added to maintain the necessary USB signal voltages on cabling even as long as 60 feet by compensating for the inherent lossiness of the transmission line.

15 It will be appreciated that the embodiments described above are merely exemplary and should not be deemed as limiting, and that the rights granted in these letters patent are defined by the following claims. For example, the present invention may be profitably incorporated into a 3-D aligner, such as that disclosed in U.S. Patent No. 5,724,743, incorporated herein by reference, to couple the camera pods to  
20 the host computer. For another example, the present invention may be used with a remote display device carried by an operator around the vehicle. In this example, the remote display device may receive a data transmission via a multi-point serial link from the host computer so that the operator may view vehicle diagnostic information remotely from any display connected to the host computer.

I claim:

1. A vehicle diagnostic system comprising:  
a general purpose computer, the computer capable of executing a vehicle diagnostic application and serving as a multi-point serial link protocol host;  
5 a multi-point serial link operably coupled to the computer and having at least one port;  
at least one vehicle diagnostic sensor operably coupled to the at least one multi-point serial link port and capable of sensing a vehicle diagnostic state associated with the at least one sensor.  
10
2. The system of claim 1 whereupon a change in the vehicle diagnostic state associated with any one sensor, the respective sensor provides an interrupt to the computer through the multi-point serial link.
- 15 3. The system of claim 2 wherein the interrupt comprises a stream of data indicative of a change in the vehicle diagnostic state.
4. The system of claim 1 wherein the system comprises a vehicle wheel alignment system, the vehicle diagnostic sensors comprise vehicle wheel alignment  
20 angle sensors, and the vehicle diagnostic state comprises a vehicle wheel alignment angle.
5. The system of claim 2 wherein the interrupt comprises a stream of data indicative of the direction and magnitude of the change in the vehicle wheel  
25 alignment angle.
6. The system of claim 2 wherein after receipt of the interrupt, the computer provides the interrupt to the vehicle diagnostic application.
- 30 7. The system of claim 1 wherein the multi-point serial link comprises a Universal Serial Bus (USB) hub.



8. The system of claim 1 wherein the multi-point serial link is located within the vehicle in operable communication with a vehicle on-board computer.

9. The system of claim 1 wherein the computer polls each of the plurality of sensors within a predetermined period of time and the respective sensors return a message comprising a stream of data to the computer through the link indicative of the vehicle diagnostic state associated with the respective sensors.

10. The system of claim 9 wherein the message comprises a stream of data indicative of vehicle diagnostic state.

11. The system of claim 9 wherein the system comprises a vehicle wheel alignment system, the vehicle diagnostic sensors comprise vehicle wheel alignment angle sensors, and the vehicle diagnostic state comprises a vehicle wheel alignment angle.

12. The system of claim 11 wherein the message comprises a stream of data indicative of the direction and magnitude of the change in the vehicle wheel alignment angle.

13. The system of claim 9 wherein after receipt of the message, the computer provides the stream of data to the vehicle diagnostic application.

14. A vehicle diagnostic system comprising:  
a general purpose computer, the computer capable of executing a vehicle diagnostic application and serving as a multi-point serial link protocol host;  
a multi-point serial link operably coupled to the computer and having at least one port;

at least one vehicle diagnostic sensor operably coupled to the multi-port serial link capable of sensing a vehicle diagnostic state associated with each respective sensor, wherein the computer is capable of instantaneously detecting the

addition or removal of a sensor to and from a port and indicating such addition or removal to the vehicle diagnostic application.

15. The system of claim 14 further comprising a second multi-point  
5 serial link operably coupled to the first link through one of the plurality of ports, the second link also comprising a plurality of ports, the computer being capable of instantaneously detecting the addition or remove of the second link to and from the ports.

10 16. The system of claim 14 wherein the vehicle diagnostic application comprises both a vehicle wheel alignment application and a vehicle engine diagnostic application, and the at least one vehicle diagnostic sensors comprises both at least one vehicle wheel angle alignment sensor and at least one engine diagnostic sensor.

15 17. A vehicle diagnostic system comprising:  
a general purpose computer, the computer capable of executing a vehicle diagnostic application and serving as a multi-point serial link protocol host;  
a hardware interface board comprising interface logic and at least one  
externally accessible serial communication port, interface logic being shared by a  
20 multi-point serial link device controller operably coupled between the computer and the interface logic and a serial communications controller operably coupled to the at least one externally accessible serial communication port;  
at least one vehicle diagnostic sensor operably coupled to the device  
controller through one of the externally accessible serial communication ports and  
25 each capable of sensing a vehicle diagnostic state associated with the at least one sensor,  
wherein the serial communications controller periodically senses the vehicle  
diagnostic state at one or more sensors and provides the vehicle diagnostic state to the  
device controller.

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18. The system of claim 17 wherein the interface logic includes at least one from the list comprising: RAM, Dual Port RAM, Bus Transceivers and Latches.

5 19. The system of claim 17 wherein the computer periodically polls the device controller and the device controller returns a message comprising a stream of data from the serial communication controller to the computer indicative of the vehicle diagnostic state associated with the at least one sensor.

10 20. A vehicle diagnostic system comprising:  
a general purpose computer, the computer capable of executing a vehicle diagnostic application and serving as a multi-point serial link protocol host;  
a multi-point serial link operably coupled to the computer and having at least one port;  
15 at least one vehicle diagnostic sensor operably coupled to the link through the at least one port and capable of sensing a vehicle diagnostic state associated with the at least one sensor through electrical coupling means capable of extending at least sixty feet from the hub.

20 21. A vehicle diagnostic system comprising:  
a general purpose computer, the computer capable of executing a vehicle diagnostic application and serving as a multi-point serial link protocol host;  
at least one vehicle diagnostic sensor comprising a multi-point serial link device controller operably coupled to the computer and capable of sensing a vehicle  
25 diagnostic state associated with the sensor, the at least one sensor comprising detection means for generating data indicative of the vehicle diagnostic state and providing the data to its device controller for later communication to the computer,  
whereby the computer may provide the data to the vehicle diagnostic application after receipt from the at least one sensor.

30

22. A vehicle diagnostic system comprising:

a general purpose computer comprising a vehicle diagnostic application; at least one sensor coupled to the vehicle diagnostic application through a multi-point serial link protocol hub, the hub communicating with the computer via a multi-point serial link protocol;

- 5            wherein the hub comprises a plurality of additional ports, whereby multi-point serial link connections to additional sensors for additional vehicle diagnostic applications may be made.

23.            A vehicle diagnostic system comprising:  
10            a general purpose computer comprising a vehicle diagnostic application; and means in the computer for receiving vehicle diagnostic information from a vehicle on-board computer via a multi-point serial link protocol.

24.            The system of claim 23 wherein the multi-point serial link  
15            protocol comprises USB.

25.            The system of claim 23 further comprising:  
                at least one vehicle diagnostic sensor operably coupled to the vehicle on-board computer,  
20            whereby the vehicle on-board computer transmits sensor data from the diagnostic sensors to the general purpose computer.

26.            The system of claim 25 wherein the at least one vehicle  
                diagnostic sensor comprises one from the list of: a wheel alignment sensor, an engine  
25            analyzer sensor, and a vehicle wheel balancer sensor.

27.            The system of claim 1 further comprising a remote display  
                operably coupled to the multi-point serial link host, whereby vehicle diagnostic  
                information may be transmitted to the remote display device over a multi-point serial  
30            link.

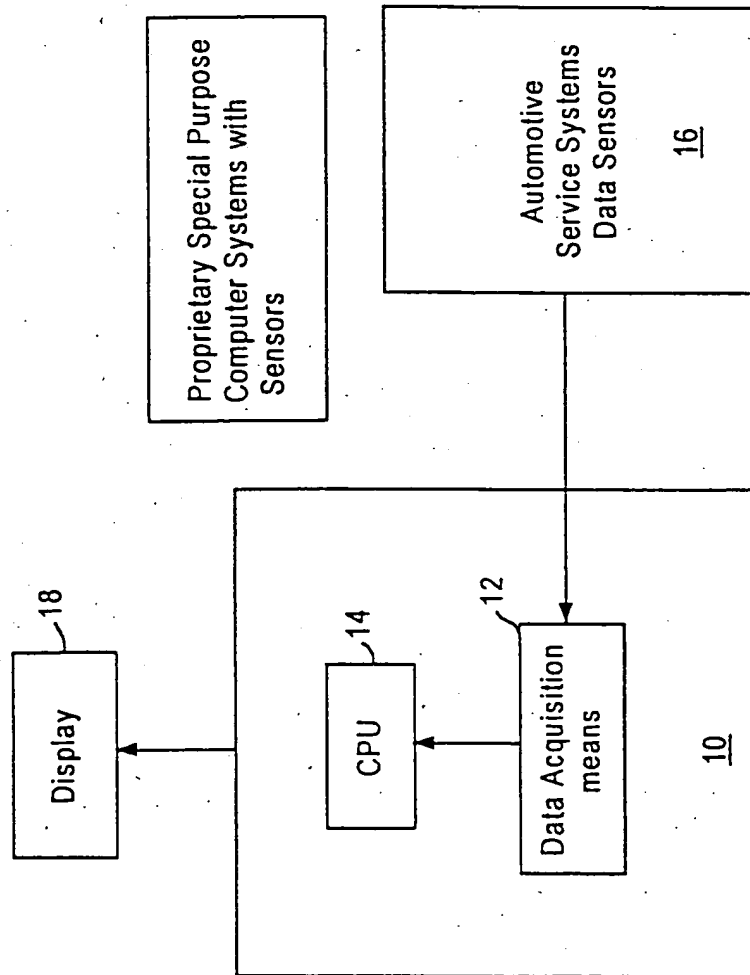


Fig. 1  
PRIOR ART

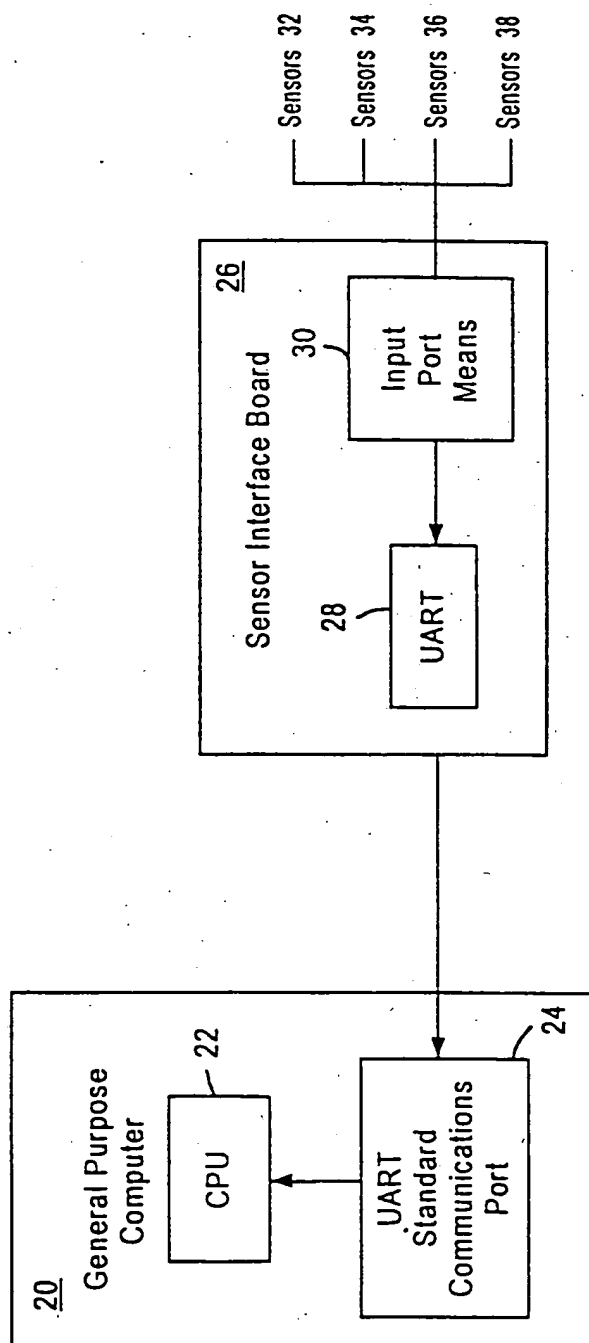


Fig. 2  
PRIOR ART

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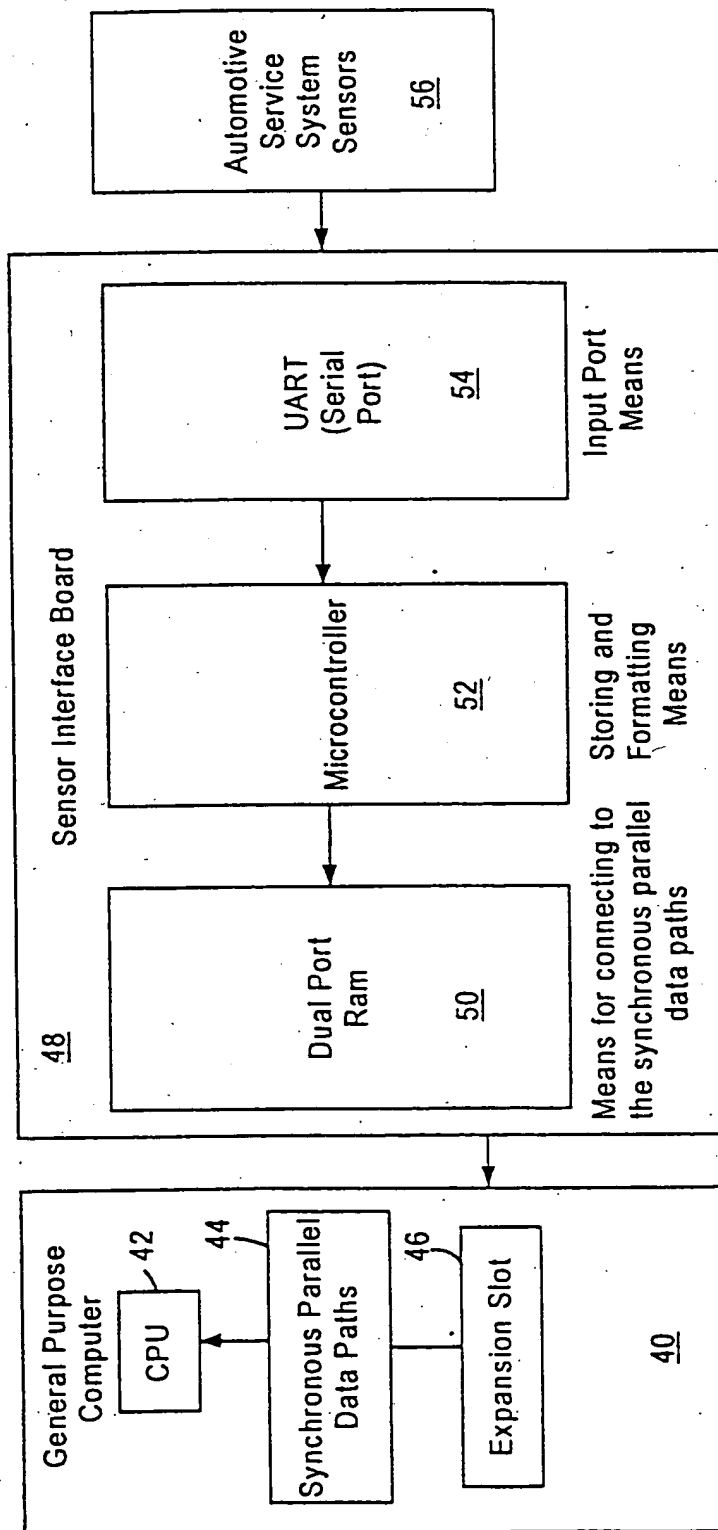


Fig.3

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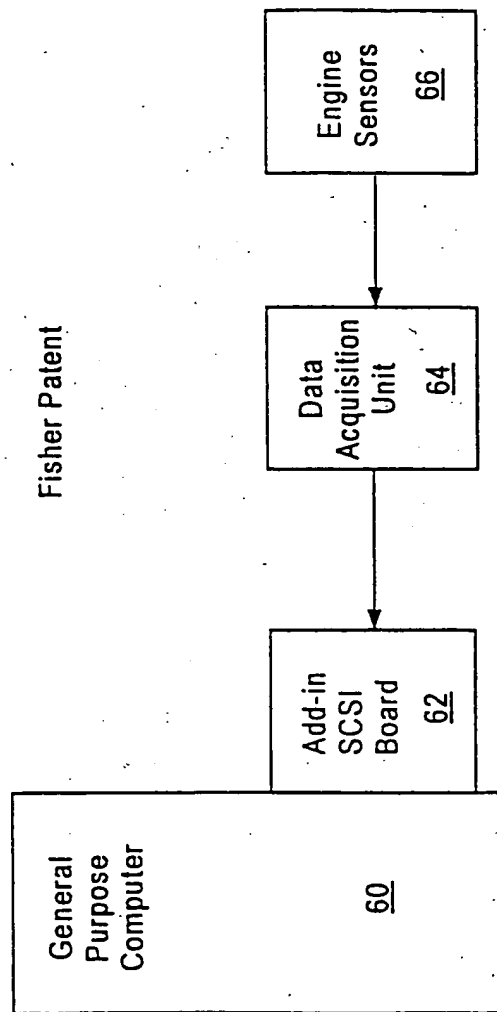


Fig. 4



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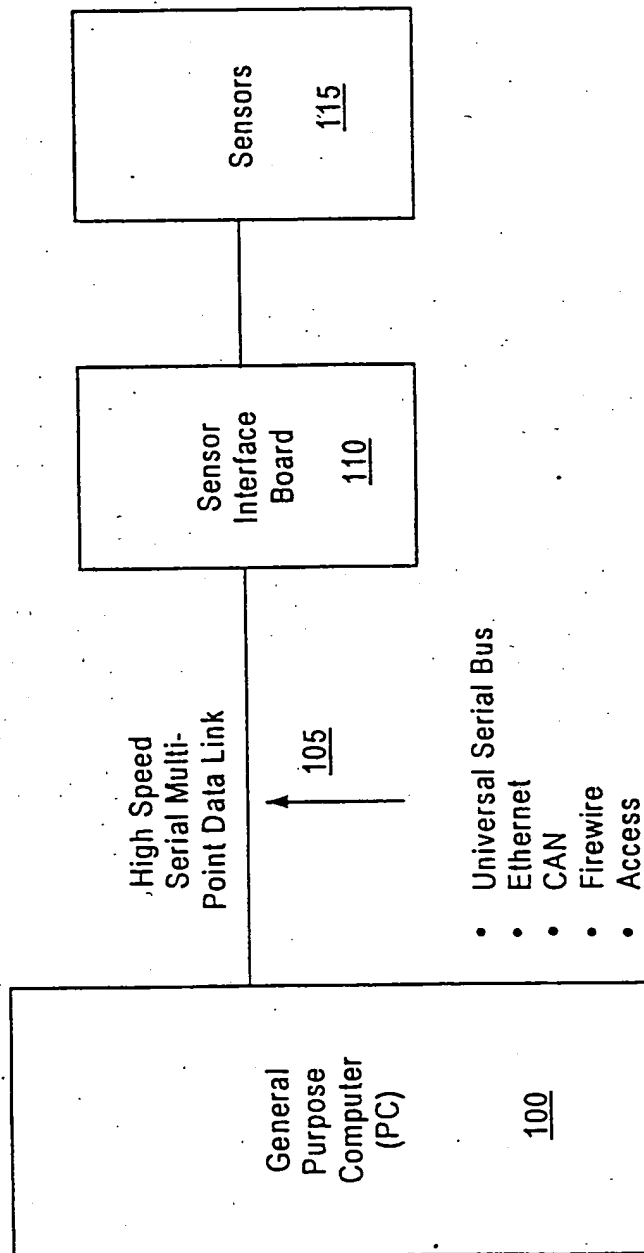


Fig. 5

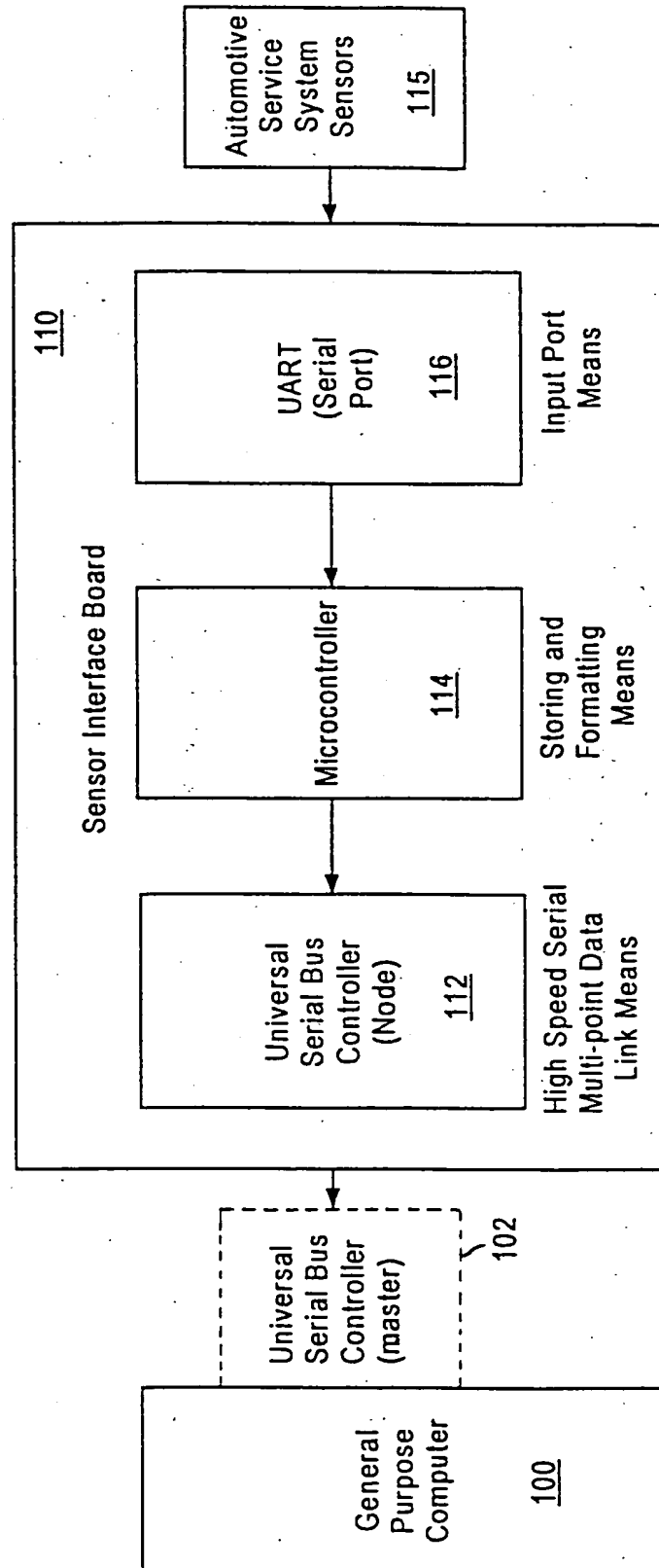


Fig. 6.

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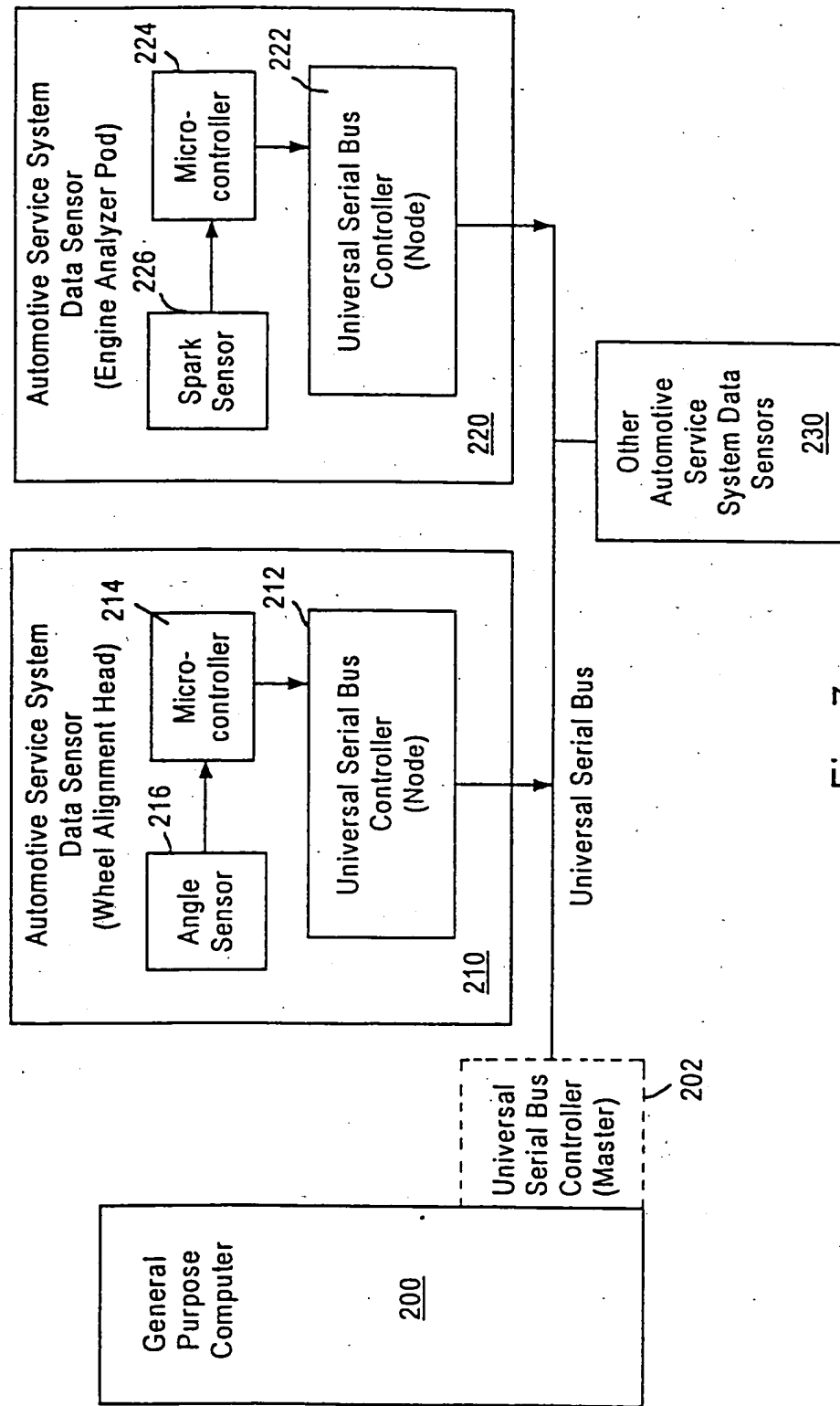


Fig. 7

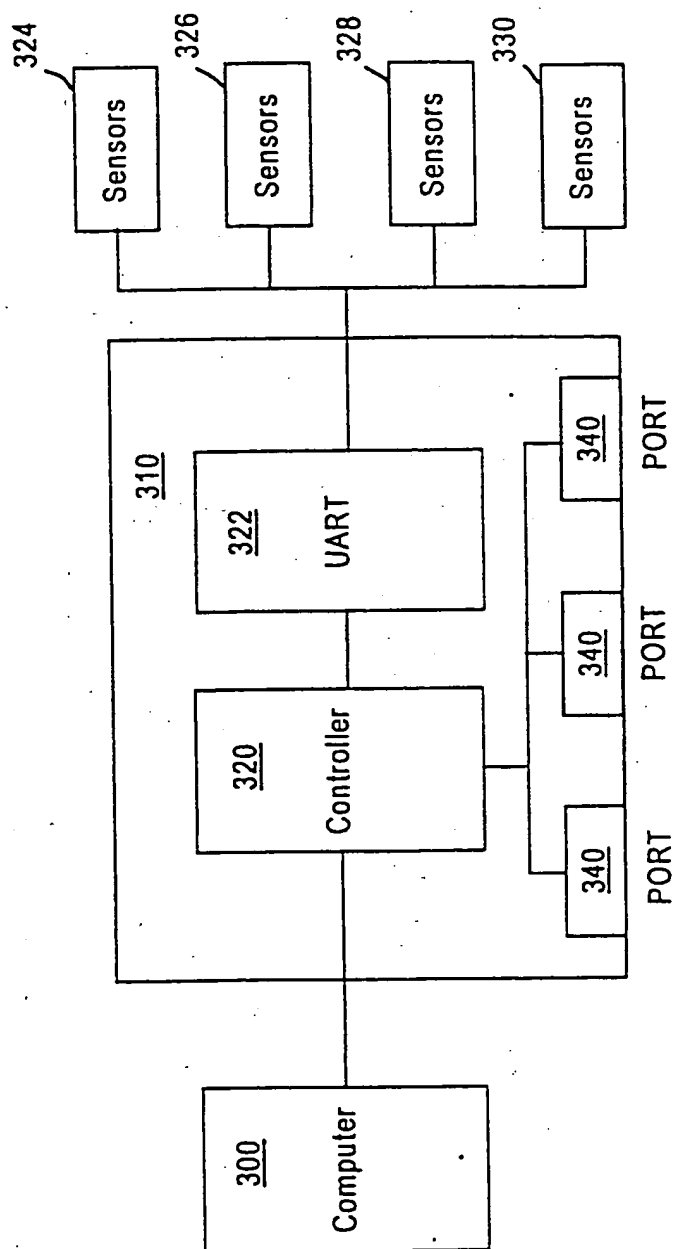


Fig. 8

# INTERNATIONAL SEARCH REPORT

International Application No

PCT/US 99/11153

A. CLASSIFICATION OF SUBJECT MATTER  
IPC 7 B60R16/02

According to International Patent Classification (IPC) or to both national classification and IPC

## B. FIELDS SEARCHED

Minimum documentation searched (classification system followed by classification symbols)  
IPC 7 B60R G01B

Documentation searched other than minimum documentation to the extent that such documents are included in the fields searched

Electronic data base consulted during the international search (name of data base and, where practical, search terms used)

## C. DOCUMENTS CONSIDERED TO BE RELEVANT

Category *	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
X	EP 0 388 107 A (HITACHI LTD) 19 September 1990 (1990-09-19)	1-3, 6-10, 13, 17-27
Y	column 7, line 18 - column 9, line 30  column 10, line 1 - column 13, line 40 column 17, line 3 - column 18, line 17 column 25, line 35 - column 27, line 47; figures 1-60	4, 5, 11, 12
Y	US 5 513 439 A (BRAUER STEPHEN F ET AL) 7 May 1996 (1996-05-07)	4, 5, 11, 12
A	column 2, line 1 - line 41 column 5, line 54 - line 62 column 6, line 30 - column 7, line 5; figures 1-17	16
	-/--	

☒ Further documents are listed in the continuation of box C.

☒ Patent family members are listed in annex.

### \* Special categories of cited documents:

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Date of the actual completion of the international search

10 September 1999

Date of mailing of the international search report

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## C.(Continuation) DOCUMENTS CONSIDERED TO BE RELEVANT

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X	US 5 758 300 A (ABE KUNIHIRO) 26 May 1998 (1998-05-26)  the whole document	1-3, 6-10,13, 17-27 4,5,11, 12 14,15
Y		
A		
Y	US 5 760 938 A (HODGE JOHN C) 2 June 1998 (1998-06-02) column 3, line 31 - column 5, line 16 column 7, line 49 - column 8, line 58; figures 1-4,17	4,5,11, 12 16
A		

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Information on patent family members

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PCT/US 99/11153

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